

คณะวิศวกรรมศาสตร์
มหาวิทยาลัยสงขลานครินทร์

การสอบกลางภาค ประจำปีภาคการศึกษาที่ 2

วันที่ 26 ธันวาคม 2547

วิชา 215-292 Dynamics

ประจำปีการศึกษา 2547

เวลา 09.00-12.00 น.

ห้อง R 201

คำสั่ง

1. ข้อสอบมีทั้งหมด 6 ข้อ ให้ทำทุกข้อ แต่ละข้อมีคะแนนเท่ากัน
2. ห้ามนำหนังสือและเอกสารใดๆ เข้าห้องสอบ
3. อนุญาตให้นำเครื่องคิดเลขเข้าห้องสอบได้

ผศ.สุวัฒน์ ไทชนะ

ผู้ออกข้อสอบ

ชื่อ-สกุล..... รหัส.....

ชื่อ-สกุล..... รหัส.....

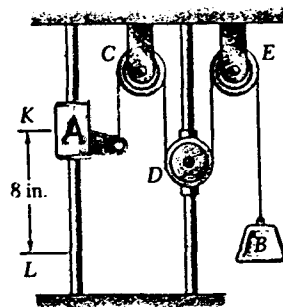
ข้อ 1. (10 คะแนน)

The position of a particle which moves along a straight line is defined by the relation $x = t^3 - 6t^2 - 15t + 40$, where x is expressed in feet and t in seconds. Determine

- the time at which the velocity will be zero,
- the position and distance traveled by the particle at that time,
- the acceleration of the particle at that time,
- the distance traveled by the particle from $t = 4$ s to $t = 6$ s.

ข้อ 2. (10 คะแนน)

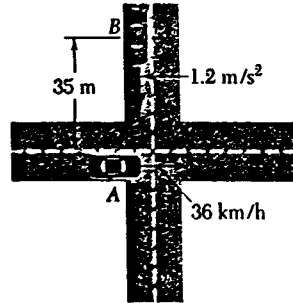
Collar A and block B are connected by a cable passing over three pulleys C , D , and E as shown. Pulleys C and E are fixed, while D is attached to a collar which is pulled downward with a constant velocity of 3 in./s. At $t = 0$, collar A starts moving downward from position K with a constant acceleration and no initial velocity. Knowing that the velocity of collar A is 12 in./s as it passes through point L , determine the change in elevation, the velocity, and the acceleration of block B when collar A passes through L .



ชื่อ-สกุล..... รหัส.....

ข้อ 3. (10 คะแนน)

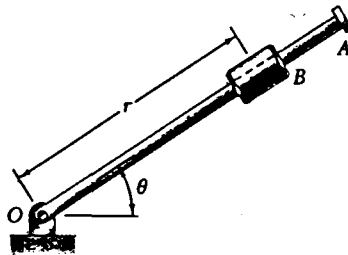
Automobile A is traveling east at the constant speed of 36 km/h. As automobile A crosses the intersection shown, automobile B starts from rest 35 m north of the intersection and moves south with a constant acceleration of B relative to A 5 s after A crosses the intersection.



ข้อ 4. (10 คะแนน)

The rotation of the 0.9-m arm OA about O is defined by the relation $\theta = 0.15t^2$, where θ is expressed in radians and t in seconds. Collar B slides along the arm in such a way that its distance from O is $r = 0.9 - 0.12t^2$, where r is expressed in meters and t in seconds. After the arm OA has rotated through 30° , determine

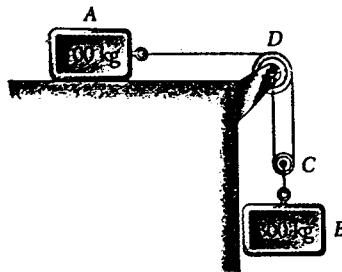
- the total velocity of the collar,
- the total acceleration of the collar,
- the relative acceleration of the collar with respect to the arm.



ชื่อ-สกุล..... รหัส.....

ข้อ 5. (10 คะแนน)

The two blocks shown start from rest. The horizontal plane and the pulley are frictionless, and the pulley is assumed to be of negligible mass. Determine the acceleration of each block and the tension in each cord.



SOLUTION \checkmark 1

The equations of motion are

$$x = t^3 - 6t^2 - 15t + 40 \quad (1)$$

$$v = \frac{dx}{dt} = 3t^2 - 12t - 15 \quad (2)$$

$$a = \frac{dv}{dt} = 6t - 12 \quad (3)$$

a. Time at Which $v = 0$. We set $v = 0$ in (2):

$$3t^2 - 12t - 15 = 0 \quad t = -1 \text{ s} \quad \text{and} \quad t = +5 \text{ s} \quad \blacktriangleleft$$

Only the root $t = +5$ s corresponds to a time after the motion has begun: for $t < 5$ s, $v < 0$, the particle moves in the negative direction; for $t > 5$ s, $v > 0$, the particle moves in the positive direction.

b. Position and Distance Traveled When $v = 0$. Carrying $t = +5$ s into (1), we have

$$x_5 = (5)^3 - 6(5)^2 - 15(5) + 40 \quad x_5 = -60 \text{ ft} \quad \blacktriangleleft$$

The initial position at $t = 0$ was $x_0 = +40$ ft. Since $v \neq 0$ during the interval $t = 0$ to $t = 5$ s, we have

$$\text{Distance traveled} = x_5 - x_0 = -60 \text{ ft} - 40 \text{ ft} = -100 \text{ ft}$$

$$\text{Distance traveled} = 100 \text{ ft in the negative direction} \quad \blacktriangleleft$$

c. Acceleration When $v = 0$. We substitute $t = +5$ s into (3):

$$a_5 = 6(5) - 12 \quad a_5 = +18 \text{ ft/s}^2 \quad \blacktriangleleft$$

d. Distance Traveled from $t = 4$ s to $t = 6$ s. The particle moves in the negative direction from $t = 4$ s to $t = 5$ s and in the positive direction from $t = 5$ s to $t = 6$ s; therefore, the distance traveled during each of these time intervals will be computed separately.

$$\text{From } t = 4 \text{ s to } t = 5 \text{ s: } \quad x_5 = -60 \text{ ft}$$

$$x_4 = (4)^3 - 6(4)^2 - 15(4) + 40 = -52 \text{ ft}$$

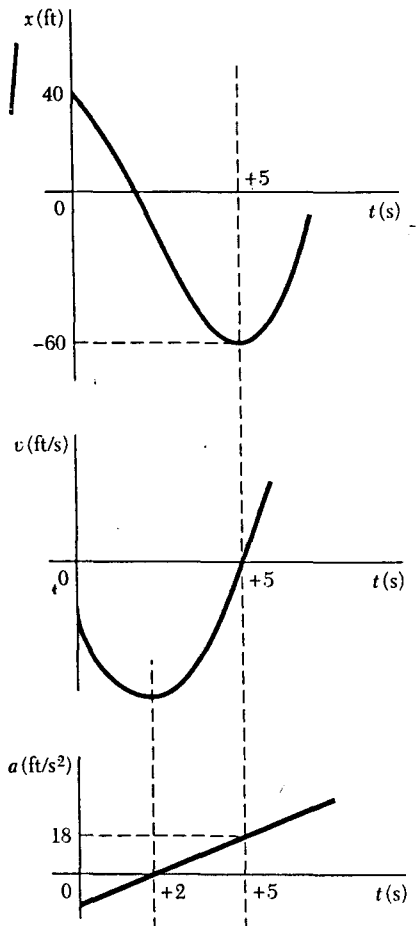
$$\begin{aligned} \text{Distance traveled} &= x_5 - x_4 = -60 \text{ ft} - (-52 \text{ ft}) = -8 \text{ ft} \\ &= 8 \text{ ft in the negative direction} \end{aligned}$$

$$\text{From } t = 5 \text{ s to } t = 6 \text{ s: } \quad x_5 = -60 \text{ ft}$$

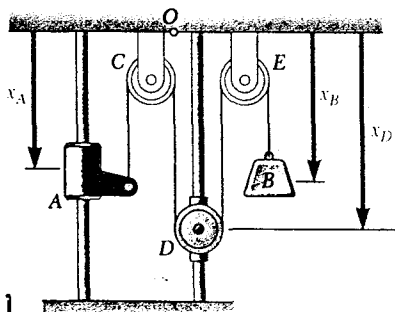
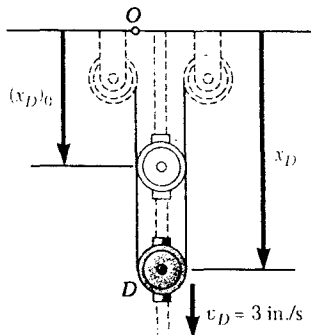
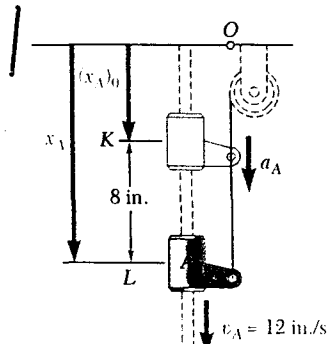
$$x_6 = (6)^3 - 6(6)^2 - 15(6) + 40 = -50 \text{ ft}$$

$$\begin{aligned} \text{Distance traveled} &= x_6 - x_5 = -50 \text{ ft} - (-60 \text{ ft}) = +10 \text{ ft} \\ &= 10 \text{ ft in the positive direction} \end{aligned}$$

$$\text{Total distance traveled from } t = 4 \text{ s to } t = 6 \text{ s is } 8 \text{ ft} + 10 \text{ ft} = 18 \text{ ft} \quad \blacktriangleleft$$



SOLUTION \checkmark 2



Motion of Collar A. We place the origin O at the upper horizontal surface and choose the positive direction downward. We observe that when $t = 0$, collar A is at the position K and $(v_A)_0 = 0$. Since $v_A = 12$ in./s and $x_A - (x_A)_0 = 8$ in. when the collar passes through L , we write

$$v_A^2 = (v_A)_0^2 + 2a_A[x_A - (x_A)_0] \quad (12)^2 = 0 + 2a_A(8)$$

$$a_A = 9 \text{ in./s}^2$$

The time at which collar A reaches point L is obtained by writing

$$v_A = (v_A)_0 + a_A t \quad 12 = 0 + 9t \quad t = 1.333 \text{ s}$$

Motion of Pulley D. Recalling that the positive direction is downward, we write

$$a_D = 0 \quad v_D = 3 \text{ in./s} \quad x_D = (x_D)_0 + v_D t = (x_D)_0 + 3t$$

When collar A reaches L , at $t = 1.333$ s, we have

$$x_D = (x_D)_0 + 3(1.333) = (x_D)_0 + 4$$

Thus,

$$x_D - (x_D)_0 = 4 \text{ in.}$$

Motion of Block B. We note that the total length of cable $ACDEB$ differs from the quantity $(x_A + 2x_D + x_B)$ only by a constant. Since the cable length is constant during the motion, this quantity must also remain constant. Thus, considering the times $t = 0$ and $t = 1.333$ s, we write

$$x_A + 2x_D + x_B = (x_A)_0 + 2(x_D)_0 + (x_B)_0 \quad (1)$$

$$[x_A - (x_A)_0] + 2[x_D - (x_D)_0] + [x_B - (x_B)_0] = 0 \quad (2)$$

But we know that $x_A - (x_A)_0 = 8$ in. and $x_D - (x_D)_0 = 4$ in.; substituting these values in (2), we find

$$8 + 2(4) + [x_B - (x_B)_0] = 0 \quad x_B - (x_B)_0 = -16 \text{ in.}$$

Thus:

$$\text{Change in position of } B = 16 \text{ in. } \uparrow \quad \blacktriangleleft$$

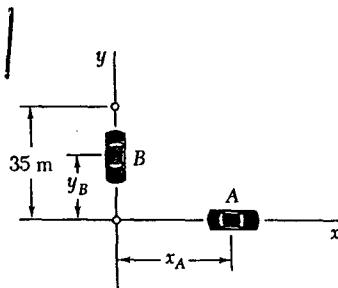
Differentiating (1) twice, we obtain equations relating the velocities and the accelerations of A , B , and D . Substituting for the velocities and accelerations of A and D at $t = 1.333$ s, we have

$$v_A + 2v_D + v_B = 0 \quad 12 + 2(3) + v_B = 0$$

$$v_B = -18 \text{ in./s} \quad \uparrow \quad \blacktriangleleft$$

$$a_A + 2a_D + a_B = 0 \quad 9 + 2(0) + a_B = 0$$

$$a_B = -9 \text{ in./s}^2 \quad \uparrow \quad \blacktriangleleft$$



SOLUTION $\checkmark 3$

We choose x and y axes with origin at the intersection of the two streets and with positive senses directed respectively east and north.

Motion of Automobile A. First the speed is expressed in m/s:

$$v_A = \left(36 \frac{\text{km}}{\text{h}}\right) \left(\frac{1000 \text{ m}}{1 \text{ km}}\right) \left(\frac{1 \text{ h}}{3600 \text{ s}}\right) = 10 \text{ m/s}$$

Noting that the motion of A is uniform, we write, for any time t .

$$\begin{aligned} a_A &= 0 \\ v_A &= +10 \text{ m/s} \\ x_A &= (x_A)_0 + v_A t = 0 + 10t \end{aligned}$$

For $t = 5 \text{ s}$, we have

$$\begin{aligned} a_A &= 0 & a_A &= 0 \\ v_A &= +10 \text{ m/s} & v_A &= 10 \text{ m/s} \rightarrow \\ x_A &= +(10 \text{ m/s})(5 \text{ s}) = +50 \text{ m} & r_A &= 50 \text{ m} \rightarrow \end{aligned}$$

Motion of Automobile B. We note that the motion of B is uniformly accelerated and write

$$\begin{aligned} a_B &= -1.2 \text{ m/s}^2 \\ v_B &= (v_B)_0 + at = 0 - 1.2t \\ y_B &= (y_B)_0 + (v_B)_0 t + \frac{1}{2} a_B t^2 = 35 + 0 - \frac{1}{2}(1.2)t^2 \end{aligned}$$

For $t = 5 \text{ s}$, we have

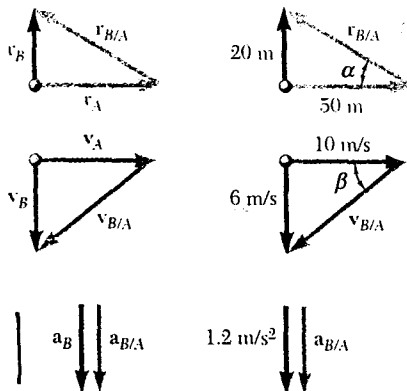
$$\begin{aligned} a_B &= -1.2 \text{ m/s}^2 & a_B &= 1.2 \text{ m/s}^2 \downarrow \\ v_B &= -(1.2 \text{ m/s}^2)(5 \text{ s}) = -6 \text{ m/s} & v_B &= 6 \text{ m/s} \downarrow \\ y_B &= 35 - \frac{1}{2}(1.2 \text{ m/s}^2)(5 \text{ s})^2 = +20 \text{ m} & r_B &= 20 \text{ m} \uparrow \end{aligned}$$

Motion of B Relative to A. We draw the triangle corresponding to the vector equation $r_B = r_A + r_{B/A}$ and obtain the magnitude and direction of the position vector of B relative to A.

$$r_{B/A} = 53.9 \text{ m} \quad \alpha = 21.8^\circ \quad r_{B/A} = 53.9 \text{ m} \angle 21.8^\circ \leftarrow$$

Proceeding in a similar fashion, we find the velocity and acceleration of B relative to A.

$$\begin{aligned} v_{B/A} &= 11.66 \text{ m/s} & v_B &= v_A + v_{B/A} & v_{B/A} &= 11.66 \text{ m/s} \angle 31.0^\circ \leftarrow \\ a_B &= a_A + a_{B/A} & a_B &= 1.2 \text{ m/s}^2 \downarrow \leftarrow \end{aligned}$$



SOLUTION \checkmark 4

Time t at which $\theta = 30^\circ$. Substituting $\theta = 30^\circ = 0.524$ rad into the expression for θ , we obtain

$$\theta = 0.15t^2 \quad 0.524 = 0.15t^2 \quad t = 1.869 \text{ s}$$

Equations of Motion. Substituting $t = 1.869$ s in the expressions for r , θ , and their first and second derivatives, we have

$$\begin{aligned} r &= 0.9 - 0.12t^2 = 0.481 \text{ m} & \theta &= 0.15t^2 = 0.524 \text{ rad} \\ \dot{r} &= -0.24t = -0.449 \text{ m/s} & \dot{\theta} &= 0.30t = 0.561 \text{ rad/s} \\ \ddot{r} &= -0.24 = -0.240 \text{ m/s}^2 & \ddot{\theta} &= 0.30 = 0.300 \text{ rad/s}^2 \end{aligned}$$

a. Velocity of B. Using Eqs. (11.45), we obtain the values of v_r and v_θ when $t = 1.869$ s.

$$\begin{aligned} v_r &= \dot{r} = -0.449 \text{ m/s} \\ v_\theta &= r\dot{\theta} = 0.481(0.561) = 0.270 \text{ m/s} \end{aligned}$$

Solving the right triangle shown, we obtain the magnitude and direction of the velocity,

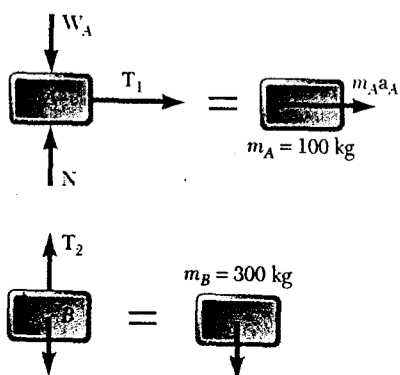
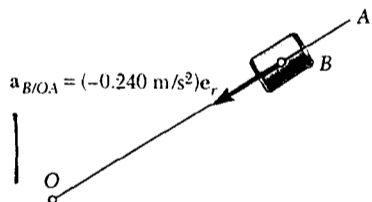
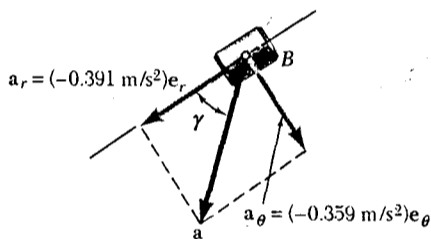
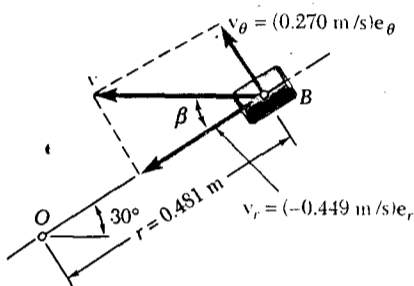
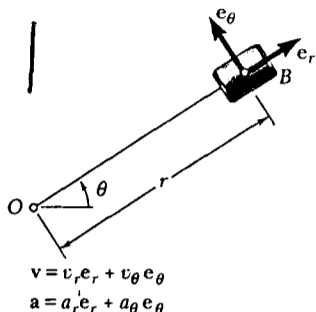
$$v = 0.524 \text{ m/s} \quad \beta = 31.0^\circ \quad \blacktriangleleft$$

b. Acceleration of B. Using Eqs. (11.46), we obtain

$$\begin{aligned} a_r &= \ddot{r} - r\dot{\theta}^2 \\ &= -0.240 - 0.481(0.561)^2 = -0.391 \text{ m/s}^2 \\ a_\theta &= r\ddot{\theta} + 2\dot{r}\dot{\theta} \\ &= 0.481(0.300) + 2(-0.449)(0.561) = -0.359 \text{ m/s}^2 \\ a &= 0.531 \text{ m/s}^2 \quad \gamma = 42.6^\circ \quad \blacktriangleleft \end{aligned}$$

c. Acceleration of B with Respect to Arm OA. We note that the motion of the collar with respect to the arm is rectilinear and defined by the coordinate r . We write

$$\begin{aligned} a_{B/OA} &= \ddot{r} = -0.240 \text{ m/s}^2 \\ a_{B/OA} &= 0.240 \text{ m/s}^2 \text{ toward } O. \quad \blacktriangleleft \end{aligned}$$



$$a_B = \frac{1}{2}a_A \quad (1)$$

Kinetics. We apply Newton's second law successively to block A, block B, and pulley C.

Block A. Denoting by T_1 the tension in cord ACD, we write

$$\rightarrow \Sigma F_x = m_A a_A: \quad T_1 = 100a_A \quad (2)$$

Block B. Observing that the weight of block B is

$$W_B = m_B g = (300 \text{ kg})(9.81 \text{ m/s}^2) = 2940 \text{ N}$$

and denoting by T_2 the tension in cord BC, we write

$$\downarrow \Sigma F_y = m_B a_B: \quad 2940 - T_2 = 300a_B$$

or substituting for a_B from (1)

SOLUTION 10.5

Kinematics. We note that if block A moves through x_A to the right, block B moves down through

$$x_B = \frac{1}{2}x_A$$

Differentiating twice with respect to t , we have

$$a_B = \frac{1}{2}a_A \quad (1)$$

Kinetics. We apply Newton's second law successively to block A , block B , and pulley C .

Block A. Denoting by T_1 the tension in cord ACD , we write

$$\pm \Sigma F_x = m_A a_A: \quad T_1 = 100a_A \quad (2)$$

Block B. Observing that the weight of block B is

$$W_B = m_B g = (300 \text{ kg})(9.81 \text{ m/s}^2) = 2940 \text{ N}$$

and denoting by T_2 the tension in cord BC , we write

$$+\downarrow \Sigma F_y = m_B a_B: \quad 2940 - T_2 = 300a_B$$

or, substituting for a_B from (1),

$$\begin{aligned} 2940 - T_2 &= 300\left(\frac{1}{2}a_A\right) \\ T_2 &= 2940 - 150a_A \end{aligned} \quad (3)$$

Pulley C. Since m_C is assumed to be zero, we have

$$+\downarrow \Sigma F_y = m_C a_C = 0: \quad T_2 - 2T_1 = 0 \quad (4)$$

Substituting for T_1 and T_2 from (2) and (3), respectively, into (4) we write

$$\begin{aligned} 2940 - 150a_A - 2(100a_A) &= 0 \\ 2940 - 350a_A &= 0 \quad a_A = 8.40 \text{ m/s}^2 \quad \blacktriangleleft \end{aligned}$$

Substituting the value obtained for a_A into (1) and (2), we have

$$\begin{aligned} a_B &= \frac{1}{2}a_A = \frac{1}{2}(8.40 \text{ m/s}^2) & a_B &= 4.20 \text{ m/s}^2 \quad \blacktriangleleft \\ T_1 &= 100a_A = (100 \text{ kg})(8.40 \text{ m/s}^2) & T_1 &= 840 \text{ N} \quad \blacktriangleleft \end{aligned}$$

Recalling (4), we write

$$T_2 = 2T_1 \quad T_2 = 2(840 \text{ N}) \quad T_2 = 1680 \text{ N} \quad \blacktriangleleft$$

We note that the value obtained for T_2 is *not* equal to the weight of block B .

