

PRINCE OF SONGKLA UNIVERSITY
FACULTY OF ENGINEERING

Final Examination: Semester 1

Academic Year: 2549

Date: 8 October 2549

Time: 9.00 - 12.00

Subject: 211-221 Fundamentals of Electric Machines

Room: A 400

คำสั่ง - ข้อสอบมีทั้งหมด 5 ข้อ ข้อละ 20 คะแนน

- อนุญาตให้ใช้เครื่องคิดเลขได้

1. A 60 Hz single-phase transformer has 200 turns on its primary winding and 500 turns on its secondary winding. The corresponding resistances are 0.242Ω and 0.076Ω respectively. The primary is connected to a 220 V sinusoidal supply and the secondary supplies 10 kVA to a load.
 - a. Determine the load voltage, secondary current and primary current
 - b. Determine the maximum flux ϕ_m in the core
 - c. Determine the equivalent resistance in primary terms.
2. A standard 5 kVA 2300/230 V distribution transformer is connected as an autotransformer to step down the voltage from 2530 V to 2300 V. The transformer connection is as shown in figure 1; the 230 V winding is section ab, the 2300 V winding is section bc. Calculate
 - a. The load power P_L
 - b. The conducted power P_c
 - c. The transformed power P_{tr}

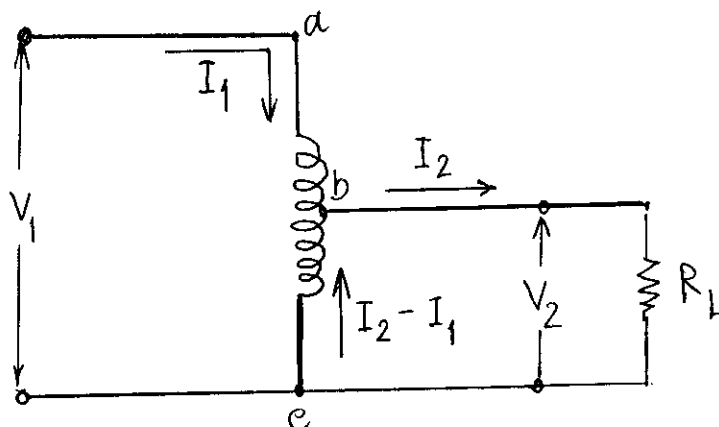


Figure 1

3. A 2300/208 V 500 kVA 60 Hz single-phase transformer was tested by means of the open-circuit test (on the low-voltage winding) and short-circuit test (on the high-voltage winding).

The test data obtained are :

$$\text{Open-circuit test : } V_{oc} = 208 \text{ V , } I_{oc} = 52.5 \text{ A , } P_{oc} = 3800 \text{ W}$$

$$\text{Short-circuit test : } V_{sc} = 95 \text{ V , } I_{sc} = 217.4 \text{ A , } P_{sc} = 6200 \text{ W}$$

Calculate

- a. The equivalent transformer parameters referred to the low-voltage side
 (R_{eL}, X_{eL}, Z_{eL})
- b. The efficiency of the transformer at rated kVA, when the power factor is 0.866 lagging
- c. The voltage regulation when supplying full load at a power factor 0.866 lagging
4. A three-phase 125 hp 440 V 60 Hz eight-pole Y-connected induction motor has the following electric circuit parameters on a per phase basis referred to stator

$$\begin{aligned} R_s &= 0.068 \ \Omega & X_s &= X'_R = 0.224 \ \Omega \\ R'_R &= 0.052 \ \Omega & X_m &= 7.68 \ \Omega \end{aligned}$$

The rotational losses are 2400 W. For a slip of 3% determine

- a. The line current and the power factor
- b. The shaft torque
- c. The efficiency *γ-connected*
5. A 5 hp 220 V 60 Hz four-pole three-phase induction motor was tested and the following data were obtained

$$\text{No-load test : } V_{NL} = 220 \text{ V , } P_{NL} = 340 \text{ W , } I_{NL} = 6.2 \text{ A}$$

$$\text{Blocked-rotor test : } V_{BR} = 49.4 \text{ V , } P_{BR} = 360 \text{ W , } I_{BR} = 13.9 \text{ A}$$

The dc resistance measurement on the stator winding gives a 4.0 V drop between terminals, when dc current flows 13.9 A. Calculate

- a. The equivalent parameters(R_e , Z_e , X_e) in stator terms
- b. The rotational loss

c. The efficiency of the motor when operating at a slip of 0.04

(Hint: The effective ac resistance is 1.25 times of the dc value)

Transformer

no load current $I_0 = I_m + I_e$

$$E_p = 4.44 f N_p \phi_m$$

$$E_s = 4.44 f N_s \phi_m$$

turn ratio $a = \frac{E_p}{E_s} = \frac{N_p}{N_s} \quad , \quad \frac{I_s}{I_p} = a$

Equivalent Circuit

$$R_{ep} = R_p + a^2 R_s \quad \left. \begin{array}{l} \\ \\ \end{array} \right\} \text{in primary term.}$$

$$X_{ep} = X_p + a^2 X_s$$

$$R_{es} = R_s + \frac{R_p}{a^2} \quad \left. \begin{array}{l} \\ \\ \end{array} \right\} \text{in secondary term.}$$

$$X_{es} = X_s + \frac{X_p}{a^2}$$

Open-circuit test

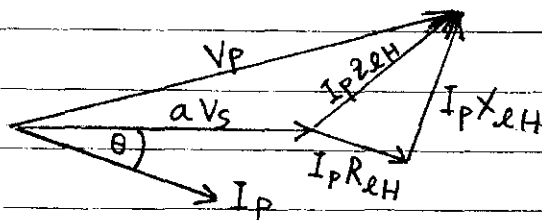
using watt-meter to measure core losses

Short-circuit Test

$$R_{eH} = \frac{P_{se}}{I_{se}^2} \quad , \quad Z_{eH} = \frac{V_{se}}{I_{se}} \quad , \quad X_{eH} = \sqrt{Z_{eH}^2 - R_{eH}^2}$$

Voltage Regulation

$$\text{voltage regulation} = \frac{V_{no-load} - V_{full-load}}{V_{full-load}} \times 100\%$$



Efficiency

$$\eta = \frac{\text{output power}}{\text{input power}} = \frac{\text{output power}}{\text{output power} + \text{losses}}$$

rotor speed $n_r = (1 - S) \times N_s \quad \text{r/min}$

rotor power input (RPI) = rotor copper loss (RCL) + rotor power developed (RPD)

$$RPI \text{ (per phase)} = I_R^2 \frac{R_R}{S}$$

$$RCL = I_R^2 R_R$$

$$RPD = I_R^2 R_R \frac{1 - S}{S} = RPI (1 - S)$$

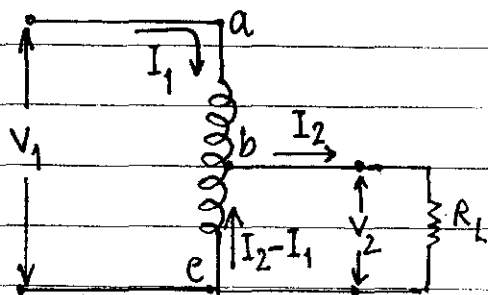
$$\eta = \frac{\text{kVA}_{\text{out}} \times \text{PF}}{\text{kVA}_{\text{out}} \times \text{PF} + \text{copper losses} + \text{core loss}}$$

The efficiency is maximum when the copper losses equal the core losses

All-day Energy Efficiency

$$\eta_e = \frac{\text{energy output over 24 hours}}{\text{energy input over 24 hours}}$$

Autotransformer



$$P_c = V_2 I_1 = \text{Conducted power to load through ab}$$

$$P_{tr} = V_2 (I_2 - I_1) = \text{transformed power to load through bc}$$

Induction Motor

$$\text{synchronous speed } n_s = \frac{120f}{P} \text{ r/min}$$

$$\text{Slip } S = \frac{n_s - n_r}{n_s} \times 100\%$$

$$\text{rotor speed } n_r = (1 - S) \times n_s \text{ r/min}$$

rotor power input (RPI) = rotor copper loss (RCL) + rotor power developed (RPD)

$$\text{RPI (per phase)} = I_R^2 \frac{R_R}{S}$$

$$\text{RCL} = I_R^2 R_R$$

$$\text{RPD} = I_R^2 R_R \frac{1 - S}{S} = \text{RPI} (1 - S)$$

$$\text{developed torque } T_d = \frac{\text{RPD}}{\omega_r} \text{ N-m.}$$

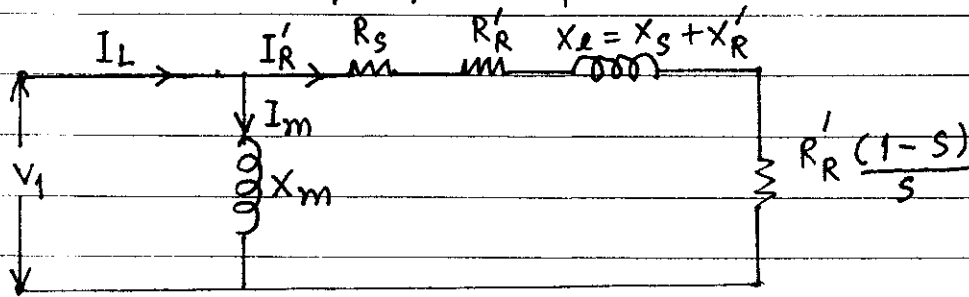
$$\omega_r = \frac{2\pi n_r}{60} \text{ rad/s}$$

$$\text{shaft torque } T = \frac{\text{RPD} - P_{rot}}{\omega_r}$$

$$P_{out} = RPD - P_{rot}$$

P_{rot} = rotational loss = friction, windage and core losses

Equivalent circuit per phase of Induction motor



เมื่อ stator winding ถูกต่อเข้ากับ แหล่งจ่ายกระแสไฟฟ้าที่ผลิต voltage ของมอเตอร์
 มี 220 V. , V_1 คือ phase voltage = $\frac{220}{\sqrt{3}}$ V.

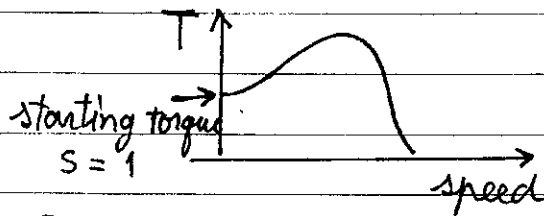
$$I_R' = \frac{V_1}{(R_s + \frac{R_R'}{s}) + j(X_s + X_R')}$$

$$I_m = \frac{V_1}{jX_m}, \quad I_L = I_m + I_R'$$

Starting Torque

$$T_{st} = \frac{RPI_{st}}{\omega_s}$$

$$\text{เมื่อ } \omega_s = \frac{2\pi n_s}{60}$$



Maximum Torque

$$s_{mt} = \frac{R_R'}{\sqrt{R_s^2 + (X_s + X_R')^2}}$$

$$T_{mt} = \frac{RPD_{mt} - P_{rot}}{\omega_{r,mt}}$$

No-load test

$$P_{NL} = P_c + P_{fr+w} + 3 I_{NL}^2 R_s$$

$$P_{rot} = P_{NL} - 3 I_{NL}^2 R_s$$

$$\therefore P_{rot} = P_c + P_{fr+w} = \text{friction} + \text{windage} + \text{core losses}$$

$$X_m = \frac{V_{NL}}{\sqrt{3} I_{NL}}$$

Blocked Rotor Test

$$Z_e = \frac{V_{BR}}{\sqrt{3} I_{BR}} = \sqrt{(R_s + R'_R)^2 + j(X_s + X'_R)^2}$$

$$R_e = \frac{P_{BR}}{3 I_{BR}^2} = R_s + R'_R$$

$$X_e = \sqrt{Z_e^2 - R_e^2} = X_s + X'_R$$

$$X_s = X'_R = 0.5 X_e$$