

PRINCE OF SONGKLA UNIVERSITY

FACULTY OF ENGINEERING

Final Examination: Semester 2

Academic Year: 2549

Date: 24 February 2550

Time: 9.00-12.00

Subject: 211-221 Fundamentals of Electrical Machines

Room: A401, A403

คำสั่ง - ข้อสอบมีทั้งหมด 5 ข้อ

- อนุญาตให้ใช้เครื่องคิดเลข และ Dictionary ได้
- ห้ามนำโน๊ต ตำราเรียน เข้าห้องสอบ

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1. In a 20 kVA 1200/120 V single-phase transformer , the resistance of primary winding is 0.242Ω and the resistance of secondary winding is 0.076Ω . Determine
 - a. the secondary current and primary current
 - b. the equivalent resistance in primary terms.
 - c. the equivalent resistance in secondary terms. (15 คะแนน)
 2. In a 50 kVA 2400/240 V transformer . the core losses and copper losses are 680 W. and 760 W, respectively. Calculate
 - a. The efficiency of this transformer at full load, when the power factor is 0.866 lagging
 - b. maximum efficiency when power factor is 0.866 (15 คะแนน)
 3. A short-circuit test was performed on a 10 kVA 2400/240 V transformer with the following data ;

$$V_{sc} = 138 \text{ V} , \quad I_{sc} = 4.17 \text{ A} , \quad P_{sc} = 202 \text{ W}$$

Calculate ;

- a. The equivalent parameters in primary terms (R_{eH}, X_{eH}, Z_{eH})
- b. The voltage regulation when supplying full load at a power factor 0.866 lagging

(20 คะแนน)

4. A three-phase 125 hp 440 V 60 Hz eight-pole Y-connected induction motor has the following electric circuit parameters on a per phase basis referred to stator

$$R_s = 0.068 \Omega \quad X_s = X'_R = 0.224 \Omega$$

$$R'_R = 0.052 \Omega \quad X_m = 7.68 \Omega$$

The rotational losses are 2400 W. For a slip of 3% determine

- a. The line current and the power factor
- b. The shaft torque
- c. The efficiency

(25 คะแนน)

5. A 5 hp 220 V 60 Hz four-pole Y-connected three-phase induction motor was tested and the following data were obtained

No-load test : $V_{NL} = 220 \text{ V}$, $P_{NL} = 340 \text{ W}$, $I_{NL} = 6.2 \text{ A}$

Blocked-rotor test : $V_{BR} = 49.4 \text{ V}$, $P_{BR} = 360 \text{ W}$, $I_{BR} = 13.9 \text{ A}$

The dc resistance measurement on the stator winding gives a 4.0 V drop between terminals, when dc current flows 13.9 A. Calculate

- a. The equivalent parameters(R_e , Z_e , X_e) in stator terms
- b. The rotational loss
- c. The efficiency of the motor when operating at a slip of 0.04

(25 คะแนน)

Transformer

$$\text{no load current } I_o = I_m + I_e$$

$$E_p = 4.44 f N_p \phi_m$$

$$E_s = 4.44 f N_s \phi_m$$

$$\text{turn ratio } a = \frac{E_p}{E_s} = \frac{N_p}{N_s}, \quad \frac{I_s}{I_p} = a$$

Equivalent Circuit

$$R_{ep} = R_p + a^2 R_s \quad \left\{ \text{in primary term.} \right.$$

$$X_{ep} = X_p + a^2 X_s \quad \left. \right\}$$

$$R_{es} = R_s + \frac{R_p}{a^2} \quad \left\{ \text{in secondary term.} \right.$$

$$X_{es} = X_s + \frac{X_p}{a^2} \quad \left. \right\}$$

Open - Circuit test

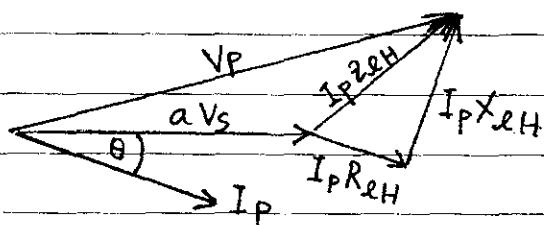
to find no-load watt-meter & core losses

Short - Circuit Test

$$R_{eh} = \frac{P_{se}}{I_{se}^2}, \quad Z_{eh} = \frac{V_{se}}{I_{se}}, \quad X_{eh} = \sqrt{Z_{eh}^2 - R_{eh}^2}$$

Voltage Regulation

$$\text{voltage regulation} = \frac{V_{no\text{-load}} - V_{full\text{-load}}}{V_{full\text{-load}}} \times 100\%$$



Efficiency

$$\eta = \frac{\text{output power}}{\text{input Power}} = \frac{\text{output power}}{\text{output power} + \text{losses}}$$

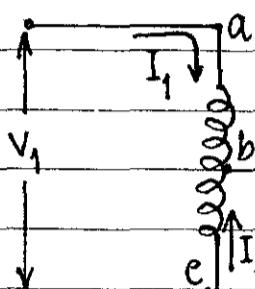
$$\eta = \frac{kVA_{out} \times PF}{kVA_{out} \times PF + \text{copper losses} + \text{core loss}}$$

The efficiency is maximum when the copper losses equal the core losses

All-day Energy Efficiency

$$\eta_e = \frac{\text{energy output over 24 hours}}{\text{energy input over 24 hours}}$$

Autotransformer



$P_c = V_2 I_1$ = Conducted power to load through ab

$P_{tr} = V_2 (I_2 - I_1)$ = transformed power to load through bc

Induction Motor

$$\text{synchonous speed } n_s = \frac{120f}{P} \text{ r/min}$$

$$\text{Slip } S = \frac{n_s - n_r}{n_s} \times 100\%$$

$$\text{rotor speed } n_r = (1 - S) \times N_s \text{ r/min}$$

$$\text{rotor power input (RPI)} = \text{rotor copper loss (RCL)} + \text{rotor power developed (RPD)}$$

$$\text{RPI (per phase)} = I_R^2 \frac{R_R}{S}$$

$$\text{RCL} = I_R^2 R_R$$

$$\text{RPD} = I_R^2 R_R \frac{1-S}{S} = \text{RPI}(1-S)$$

$$\text{developed torque } T_d = \frac{\text{RPD}}{\omega_r} \text{ N-m.}$$

$$\omega_r = \frac{2\pi n_r}{60} \text{ rad/s}$$

$$\text{shaft torque } T = \frac{\text{RPD} - \text{Prot}}{\omega_r}$$

Maximum Torque

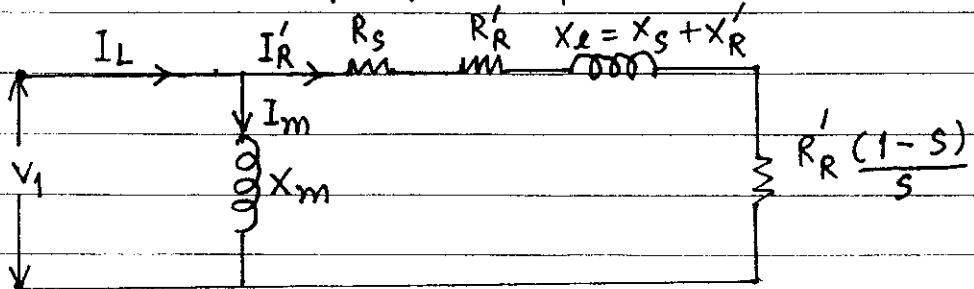
$$S_{mt} = \frac{R'_R}{\sqrt{R_s^2 + (X_s + X'_R)^2}}$$

$$T_{mt} = \frac{\text{RPD}_{mt} - \text{Prot}}{\omega_{r,mt}}$$

$$P_{out} = RPD - Prot$$

$P_{rot} = \text{rotational loss} = \text{friction, windage and core losses}$

Equivalent circuit per phase of Induction motor



ເວັບ stator winding ກາງຕ່າງໆແນວຍ 110: ເນື້ອດັນນຳກ່າວພົກສອງ voltage 200/200/200
 ດົກ 220 V. , V_1 ສະເໜີ phase voltage = $\frac{220}{\sqrt{3}}$ V.

$$I_R' = \frac{V_1}{(R_s + \frac{R'_R}{s}) + j(x_s + x'_R)}$$

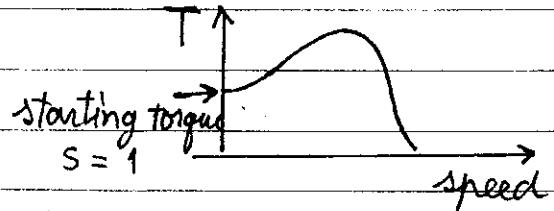
$$I_m = \frac{V_1}{jX_m} \quad , \quad I_L = I_m + I_R$$

Starting Torque

$$T_{st} = \frac{RPI_{st}}{\omega_s}$$

starting
S =

$\omega_0 \omega_s = \frac{2\pi n_s}{60}$



Maximum Torque

$$S_{mt} = \frac{R'_R}{\sqrt{R_s^2 + (x_s + x'_R)^2}}$$

$$T_{mt} = \frac{RPD_{mt} - P_{rot}}{w_{x,mt}}$$

No-load test

$$P_{NL} = P_C + P_{fr+w} + 3 I_{NL}^2 R_S$$

$$P_{rot} = P_{NL} - 3 I_{NL}^2 R_S$$

$\therefore P_{rot} = P_C + P_{fr+w}$ = friction + windage + core losses

$$X_m = \frac{V_{NL}}{\sqrt{3} I_{NL}}$$

Blocked Rotor Test

$$Z_e = \frac{V_{BR}}{\sqrt{3} I_{BR}} = \sqrt{(R_S + R'_R) + j(x_S + x'_R)}$$

$$R_e = \frac{P_{BR}}{3 I_{BR}^2} = R_S + R'_R$$

$$x_e = \sqrt{Z_e^2 - R_e^2} = x_S + x'_R$$

$$x_S = x'_R = 0.5 x_e$$