

PRINCE OF SONGKLA UNIVERSITY
FACULTY OF ENGINEERING

Final Examination: Semester 1

Academic Year: 2009

Date: September 29, 2009

Time: 9.00-12.00

Subject: 226-433: Industrial Automatic Control

Room: R300

Instructions

- There are 5 questions in 4 pages.
- Attempt all questions, write your answers in the book provided.
- Only the hand-written note on a 2-sided A4 sheet and a calculator are allowed. *Dictionary is not allowed.*
- Total score is 100.

Name:	Student ID.....
-------------	-----------------

Question #	Full Score	Assigned Score
1	15	
2	20	
3	20	
4	25	
5	20	
Total	100	

Assoc. Prof. Somchai Chuchom

Question #1 (15 marks) Briefly explain the following questions.

1.1 What is overshoot? How to reduce it?

.....
.....
.....
.....

1.2 Specify the parameters indicating the performance of the control system at the transient state.

.....
.....
.....
.....

1.3 What are the dominant poles?

.....
.....
.....
.....

1.4 BIBO stability means

.....
.....
.....
.....

1.5 What is damping ratio ?

.....
.....
.....
.....

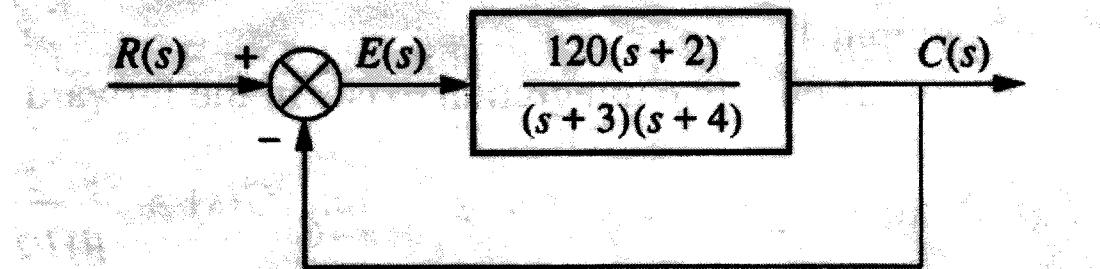
1.6 What is PLC? Explain the concept and the purpose of applying PLC in the manufacturing industry.

.....
.....
.....
.....

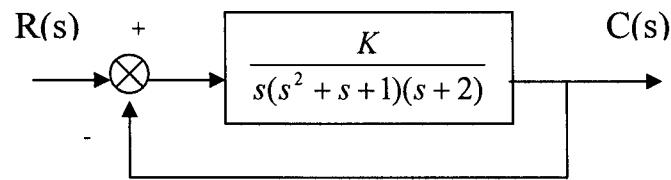


Question #2 (20 marks)

Find the steady-state error for the unit step input, $u(t)$ to the system shown in Figure 1

**Figure 1****Question #3** (20 marks)

Determine the range of K for stability of the control system shown in Figure 2.

**Figure 2**

Question #4 (25 marks)

Given a feedback system whose open-loop transfer function is

$$\frac{K(s + 20)}{(s + 2)(s + 4)(s + 10)},$$

where K is the feedback gain. Apply the root-locus technique to evaluate the system's closed-loop behaviors;

- a) The number of asymptotes, the asymptote angles, and the asymptotes' real-axis intercept.
- b) Sketch the root-locus and indicate all information needed for it.
- c) What you have learned from the root-locus sketch in b)?

Question #5 (20 marks)

A negative feedback control system has a transfer function

$$G(s) = \frac{K}{(s + 3)},$$

We select a compensator

$$G_c(s) = \frac{s + a}{s},$$

in order to achieve zero steady-state error for a step input. Select a and K so that the overshoot to a step is approximately 5% and the setting time (with a 2% criterion) is approximately 1 second.